

T-LSM Series Datasheet



- 25, 50, 100, 150 and 200 mm travel
- 10 kg load capacity
- Up to 29 mm/s speed and up to 55 N thrust
- Our most compact motorized stage with built-in controllers
- Built-in controller; daisy-chains data and power with other T-Series products

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Zaber's T-LSM Series devices are computer-controlled motorized linear stages with high thrust and speed capabilities and a very compact size. They are stand-alone units requiring only a standard 15 V power supply. An optional knob provides smooth manual control at variable speeds in both directions for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other T-Series products. The daisy-chain also shares power, making it possible for multiple T-Series products to share a single power supply. Convenient 6-pin mini din cables on the unit allow for direct interconnection between units in close proximity. For longer distances, a standard cable extension can be used.

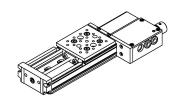
At only 21 mm high, these miniature stages are excellent for applications where a small profile is required. The T-LSM's innovative design allows speeds up to 29 mm/s and loads up to 10 kg. Like all of Zaber's products, the T-LSM Series is designed to be 'plug and play' and very easy to set up and operate. If you are considering a multi-axis system, in the XY configuration, these stages make excellent microscope stages. Adding a X-JOY3 joystick controller allows manual control of both X and Y or XYZ axes from a single interface as well as allowing microscope stage positions to be saved and recalled at the touch of a button.

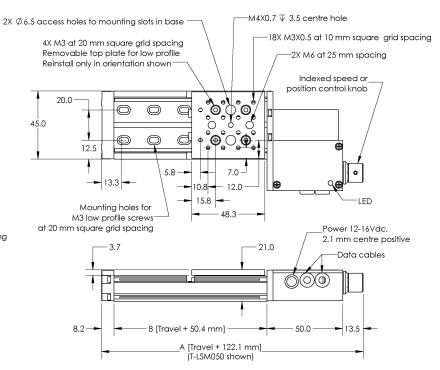
Drawings

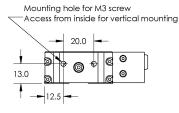


Model Number*	Travel	Α	В
T-LSM025	25.4	147.5	75.8
T-LSM050	50.8	172.9	101.2
T-LSM100	101.6	223.7	152.0
T-LSM150	152.4	274.5	202.8
T-LSM200	203.2	325.3	253.6

^{*}See product page for complete list of available models at www.zaber.com







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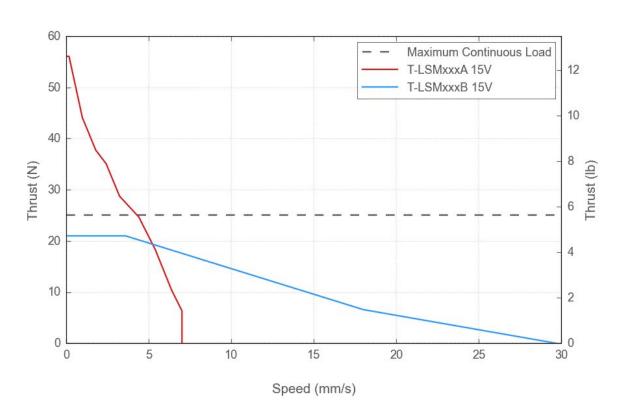
Specifications

Specification Value Alternate Unit Built-in Controller Yes Microstep Size (Default Resolution) 0.047625 µm Travel Range 25.4 mm 1.000 " Accuracy (unidirectional) 15 µm 0.000591 " Repeatability < 3 µm < 0.000118 " Backlash < 12 µm < 0.000472 " Maximum Speed 7 mm/s 0.276 "/s Minimum Speed 0.00022 mm/s 0.000009 "/s Speed Resolution 0.00022 mm/s 0.000009 "/s Encoder Type None			
Microstep Size (Default Resolution) 0.047625 μm 1.000 ° Travel Range 25.4 mm 1.000 ° Accuracy (unidirectional) 15 μm 0.000591 " Repeatability < 3 μm	Specification	Value	Alternate Unit
Travel Range 25.4 mm 1.000 " Accuracy (unidirectional) 15 μm 0.000591 " Repeatability < 3 μm	Built-in Controller	Yes	
Accuracy (unidirectional) 15 μm 0.000591 " Repeatability < 3 μm	Microstep Size (Default Resolution)	0.047625 μm	
Repeatability < 3 µm	Travel Range	25.4 mm	1.000 "
Backlash < 12 μm	Accuracy (unidirectional)	15 μm	0.000591 "
Maximum Speed 7 mm/s 0.276 "/s Minimum Speed 0.00022 mm/s 0.000099 "/s Speed Resolution 0.00022 mm/s 0.000009 "/s Encoder Type None 12.3 lb Peak Thrust 55 N 12.3 lb Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232 Communication Protocol Zaber Binary Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 μm	Repeatability	< 3 µm	< 0.000118 "
Minimum Speed 0.00022 mm/s 0.000099 "/s Speed Resolution 0.00022 mm/s 0.0000099 "/s Encoder Type None 12.3 lb Peak Thrust 55 N 12.3 lb Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232	Backlash	< 12 μm	< 0.000472 "
Speed Resolution 0.00022 mm/s 0.00009 "/s Encoder Type None 12.3 lb Peak Thrust 55 N 12.3 lb Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232 Communication Protocol Zaber Binary Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 µm	Maximum Speed	7 mm/s	0.276 "/s
Encoder Type None Peak Thrust 55 N 12.3 lb Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232 Communication Protocol Zaber Binary Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 µm	Minimum Speed	0.00022 mm/s	0.000009 "/s
Peak Thrust 55 N 12.3 lb Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232	Speed Resolution	0.00022 mm/s	0.000009 "/s
Maximum Continuous Thrust 25 N 5.6 lb Communication Interface RS-232	Encoder Type	None	
Communication Interface RS-232 Communication Protocol Zaber Binary Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 μm	Peak Thrust	55 N	12.3 lb
Communication Protocol Zaber Binary Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 µm	Maximum Continuous Thrust	25 N	5.6 lb
Maximum Centered Load 100 N 22.4 lb Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 μm	Communication Interface	RS-232	
Maximum Cantilever Load 300 N-cm 424.8 oz-in Guide Type Needle roller bearing Vertical Runout < 8 μm	Communication Protocol	Zaber Binary	
Guide Type Needle roller bearing Vertical Runout < 8 μm	Maximum Centered Load	100 N	22.4 lb
Vertical Runout < 8 μm	Maximum Cantilever Load	300 N-cm	424.8 oz-in
Horizontal Runout < 12 µm	Guide Type	Needle roller bearing	
Pitch 0.02 ° 0.349 mrad 0.02 ° 0.349 mrad 0.02 ° 0.349 mrad 0.02 ° 0.349 mrad 0.03 ° 0.524 mrad 0.0524	Vertical Runout	< 8 µm	< 0.000315 "
Roll 0.02 ° 0.349 mrad Yaw 0.03 ° 0.524 mrad Maximum Current Draw 500 mA	Horizontal Runout	< 12 μm	< 0.000472 "
Yaw0.03 °0.524 mradMaximum Current Draw500 mA	Pitch	0.02 °	0.349 mrad
Maximum Current Draw 500 mA Power Supply 12-16 VDC Power Plug 2.1 mm center positive Linear Motion Per Motor Rev 0.6096 mm 0.024 " Motor Steps Per Rev 200 Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Roll	0.02 °	0.349 mrad
Power Supply 12-16 VDC Power Plug 2.1 mm center positive Linear Motion Per Motor Rev 0.6096 mm 0.024 " Motor Steps Per Rev 200 Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Yaw	0.03 °	0.524 mrad
Power Plug 2.1 mm center positive Linear Motion Per Motor Rev 0.6096 mm 0.024 " Motor Steps Per Rev 200 Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Maximum Current Draw	500 mA	
Linear Motion Per Motor Rev 0.6096 mm 0.024 " Motor Steps Per Rev 200 Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Power Supply	12-16 VDC	
Motor Steps Per Rev 200 Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Power Plug	2.1 mm center positive	
Motor Type Stepper (2 phase) Inductance 1.5 mH/phase	Linear Motion Per Motor Rev	0.6096 mm	0.024 "
Inductance 1.5 mH/phase	Motor Steps Per Rev	200	
· ·	Motor Type	Stepper (2 phase)	
Default Resolution 1/64 of a step	Inductance	1.5 mH/phase	
Bolada Noodialion 1701 of a clop	Default Resolution	1/64 of a step	

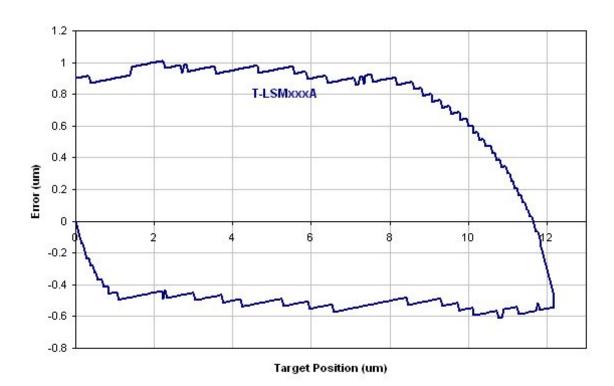
Specification	Value	Alternate Unit
Data Cable Connection	Minidin 6 pin M/F	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic hall sensor	
Manual Control	Yes	
Axes of Motion	1	
LED Indicators	Yes, Bi-Colour	
Mounting Interface	M3 and M6 threaded holes and M4 threaded center hole	
Vacuum Compatible	No	
Operating Temperature Range	0 to 50 °C	
Stage Parallelism	< 25 µm	< 0.000984 "
RoHS Compliant	Yes	
CE Compliant	Yes	
Weight	0.31 kg	0.683 lb

Charts

Thrust Speed Performance



T-LSMxxxA Microstepping Error



T-LSMxxxB Microstepping Error

